# **REACT** GNSS SMART ANTENNA

# PRECISION PERFORMANCE IN THE TOUGHEST CONDITIONS



REACT (Receiver Antenna Compact Technology) is a compact, rugged enclosure containing a high quality GNSS receiver, antenna offering a cost effective and flexible solution to your requirements. REACT provides the latest technology for precise positioning, velocities, heading and attitude using GNSS on its own or inertial navigation.

## **FUTURE PROOF**

With a multi-frequency and multi-constellation engine, REACT can be scaled to suit the application and can be upgraded through software when requirements change.

### SCALABLE PRECISION PERFORMANCE

REACT can operate as a single position to 1.5m or upgraded to use correction sources and achieve positions as precise as 1cm (RTK). The REACT is well suited to operate as an RTK base station or a rover and can be configured to output GNSS heading. REACT can be connected to an IMU to create an Inertial Navigation System.

## **BUILT FOR RUGGED ENVIRONMENTS**

REACT has been qualification tested against a strict set of standards to ensure that the system can operate in harsh environments. The compact, rugged enclosure is MIL-STD qualified with respect to EMC, shock, vibration and environmental standards. A full list is found on the back of the data sheet.

#### **INTERFERENCE PROTECTION**

High performance NovAtel OEM7 receiver provides options for signal protection against interference and jamming.

## **REACT VARIANTS**

The REACT is a modular product which can be constructed to meet a variety of applications. The R models contain a single frequency L1 GPS + GLONASS antenna, for dual frequency L1/L2 or L1/L5 quad constellation a Q model is required.

NS models provide RS232/422, USB and CAN communication ports in addition to PPS and event strobes with options of straight or right angled I/O connector cables. The NSc models have an integrated centre feed I/O cable from the base of the unit.



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## **REACT SPECIFICATIONS**

1.5m

1.2m

0.6m

0.4m

<10 sec

20 ns RMS

515 m/s

1cm + 1ppm

0.1° (2m), 0.05° (4m)<sup>4</sup>

0.2° (2m), 0.01° (4m)<sup>4</sup>

## PERFORMANCE<sup>1</sup>

#### Horizontal Position Accuracy (RMS)

Single Point L1 Single Point L1/L2 SBAS<sup>2</sup> DGPS RTK **RTK** Initialisation Time

Azimuth Accuracy<sup>3</sup> (ALIGN) Roll, Pitch Acuracy<sup>3</sup> (ALIGN) Time Accuracy Velocity Accuracy Velocitv<sup>5</sup> Vibration

**Channel Configuration** 

Up to 555 Channels<sup>12</sup> ReACT-RNS ReACT-QNS L1/L2

ReACT-QNS L1/L5

GPS L1, GLONASS L1 GPS L1/L2, GLONASS G1/G2/G3, Galileo E1/E5b, BeiDou B1/B

Galileo E1/E5a, BeiDou B1/B2a, NavIC L5

GPS L1/L5, GLONASS G1,

0.03 m/s RMS - 0.05 m/s RMS

Up to 20G (sustained tracking)

## Measurement Precision (RMS)

L1 Carrier Phase 0.50mm (differential channel) L1C/ACode 4cm L2 P(Y) Code<sup>7</sup> L2 Carrier Phase 1.00mm (differential channel) 8cm L5 Carrier Phase 0.50mm (differential Channel) 3cm L5 Code

Data Rates (Measurements and Positions) Up to 100Hz

Time to First Fix Cold Start<sup>8</sup>

< 50 sec Hot Start<sup>9</sup> <35 sec **Signal Reacquisition** L1 0.5 sec (typical) 1.0 sec (typical)

L2 & L5 RTK position reacquisition<sup>10</sup>

1-Typical values. Performance specifications subject to GPS system characteristics, US DOD operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multipath effects and the presence of intentional or unintentional interference sources. Independent tests performed at FSL office using L1L2 GPS+GLO showed improved performance figures than the stated typical values 2-SBAS includes WAAS, EGNOS and MSAS type systems, GPS only.

5-8 sec

3-Accuracy obtained using a baseline length of 2 to 4 metres

4-Time accuracy does not include biases due to RF or antenna delay

5-Export licensing restrictions apply

6-Dependant on receiver model installed

7-L2 P for GLONASS 8-Typical value. No almanac or ephemeris and no approximate position or time.

9-Typical value. Almanac and recent ephemeris saved and approximate position and time entered

10-After a complete loss of satellite signals this is the typical period the receiver takes to compute an acceptable

position in a high dynamics scenario.

11-GPSI 1/L2 GLONASSI 1/L2

12 - Depends on hardware model

## PHYSICAL AND ELECTRICAL

Dimensions

Weight

Input voltage

Data Cable Length

NS/D5: 116mm x 116mm x 84mm NSc/D5c: 116mm x 116mm x 79mm 5m 1m ('c' Models with centre mount cable) ~600g +9 to +36 VDC Power consumption at typical values <3W<sup>12</sup> typical

**Communication Ports** 

1×RS232/RS422 1x RS232 2x RS232 EDGE-WARE ports (D5 Model) 1x CAN 1Mbps (D5 model) 1x USB 2.0, 12 Mbps Auxiliary strobe signals, including a configurable PPS output for time synchronization and mark.

## FEATURES AND MOUNTING

3x M6 for plate mounting (standard) 3x 10-32 UNF for plate mounting (optional) 5/8" thread for centre mounting (NS/D5 only) Field-upgradeable software PAC multipath mitigating technology Differential GPS positioning Differential correction support for RTCM 2.1, 2.3, 3.0, 3.1, CMR, CMR+ and RTCA EDGE-WARE Modules

-32°C to +75°C

-40°C to +85°C

## **ENVIRONMENTAL**

Temperature

Operating Storage **Regulatory:** 

EMC

EMC Immersion Humidity Salt Spray Sand and Dust Fluids Susceptibility Vibration

#### Shock Electrostatic Discharge (ESD)

Ultraviolet Light Protection

Compliancy

European CE, 89/ EEC EN 55022 Class B, EN50082-1 MIL-STD-461F (Ground, Army), FCC Class A MIL-STD 810F, method 512.4, IEC 60529 IPX7 MIL-STD 810F, method 507.4, procedure 1 MIL-STD 810F, method 509.4 MIL-STD 810F, method 510.4 MIL-STD-810F, method 504 MIL-STD 810F, method 514.5, Category 20 MIL-STD 810E, method 514.4 tbl. 514.4-AXVII MIL-STD 810F, method 516.5, Procedure I, IV IEC 61000-4-2 level 2 (± 4 KV) MIL-STD-810F, method 505.4

**RoHS**, WEEE



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