SPAN CPT7

Compact Dual Antenna Enclosure With SPAN GNSS+INS Technology Delivers 3D Position, Velocity and Attitude

World-Leading GNSS+INS Technology

SPAN GNSS+INS technology brings together two different but complementary technologies: Global Navigation Satellite System (GNSS) positioning and inertial navigation. The absolute accuracy of GNSS positioning and the stability of Inertial Measurement Unit (IMU) gyro and accelerometer measurements are deeply coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when satellite signals are blocked.

SPAN CPT7 Overview

The SPAN CPT7 is a compact, single enclosure GNSS+INS receiver, powered by world class OEM7 technology by Hexagon | NovAtel. Capable of delivering up to centimeter-level accuracy, customers can choose from a variety of positioning modes to ensure they have the optimal level of accuracy for their application.

The SPAN CPT7 contains a high performing and highly reliable Honeywell HG4930 Micro Electromechanical System (MEMS) IMU to deliver leading-edge SPAN technology by NovAtel in an integrated, single enclosure solution. It provides tactical grade performance for unmanned vehicles, mobile mapping and other commercial and/or military guidance applications. The SPAN CPT7 is a small, lightweight and low-power solution with multiple communication interfaces for easy integration on multiple platforms.

SPAN CPT7 Advantages

The deep coupling of the GNSS and IMU measurements delivers the most satellite observations and the most accurate, continuous solution possible. Further, SPAN CPT7 is comprised entirely of commercial components, simplifying export restrictions involved with traditional GNSS+INS systems.

Improve SPAN CPT7 Accuracy

SPAN CPT7 provides your choice of accuracy and performance, from decimeter to RTK-level positioning. For more demanding applications, Inertial Explorer post-processing software can be used to post-process the real-time SPAN GNSS+INS solution to provide the system's highest level of accuracy.

Benefits

- High performance SPAN GNSS+INS solution
- Small, low-power, all-in-one GNSS+INS enclosure
- Easy integration into space and weight constrained applications
- Commercially exportable system
- Rugged design ideal for challenging environments
- Enhanced connection options including serial, USB, CAN and Ethernet
- Future-proof for upcoming GNSS signal support

Features

- MEMS Gyros and Accelerometers
- Small size, rugged and lightweight
- TerraStar correction services supported over multi-channel L-Band and IP connections
- Advanced interference mitigation features
- SPAN GNSS+INS capability with configurable application profiles
- Dual antenna ALIGN heading

SPAN System Performance[1]

Signal Tracking[2, 3]

GPS	L1 C/A, L1C, L2C, L2P, L5
GLONASS[4]	L1 C/A, L2 C/A, L2P, L3, L5
BeiDou[5]	B1I, B1C, B2I, B2a, B2b
Galileo[6]	E1, E5 AltBOC, E5a, E5b
NavIC (IRNSS)	L5
SBAS	L1, L5
QZSS	L1 C/A, L1C, L2C, L5
L-Band (Primary RF only)	up to 5 channels

Horizontal Position Accuracy (RMS)

Single Point L1	1.5 m
Single Point L1/L2	1.2 m
SBAS[7]	60 cm
DGPS	40 cm
TerraStar-L[8]	40 cm
TerraStar-C PRO[8]	2.5 cm
TerraStar-X[8]	2.0 cm
RTK	1 cm + 1 ppm
Initialization time < 10 s	
Initialization reliability > 99.9%	

ALIGN Heading Accuracy

Baseline	Accuracy (RMS)
2 m	0.08 deg
4 m	0.05 deg

Heave Performance[9]

Instantaneous Heave	5 cm or 5%
Delayed Heave	3.5 cm or 3.5%
Post-Processed Heave[10]	2.5 cm or 2.5%

Maximum Data Rate

IMU Raw Data Rate	100 Hz
INS Solution	Up to 200 Hz

Time to First Fix

Cold start[11]	< 39 s (typ)
Hot start[12]	< 20 s (typ)

Signal Reacquisition

L1	< 0.5 s (typ)
L2/L5	< 1.0 s (typ)

Time Accuracy[13] 20 ns RMS

Velocity Accuracy < 0.03 m/s RMS

Velocity Limit[14] 515 m/s

IMU Performance[15]

Gyroscope Performance

Technology	MEMS
Input rate (max)	±200°/s

Accelerometer Performance

Technology	MEMS
Range	±20 g

Physical and Electrical

Dimensions[16] 90 x 60 x 60 mm

Weight 500 g

Power

Power consumption[17]	7 W (typ)
Input voltage	+9 to +32 VDC

Antenna LNA Power Output

Output voltage	5 VDC ±5%
Maximum current	200 mA

Input/Output Connectors

Antennas	2 x SMA
Power and I/O	2 x Fischer Core 16 pin DPBU 104 A086 140G/240G

Communication Ports

RS-422	1
RS-232 (230400 bps max)	1
USB Device	1
Ethernet	1
CAN Bus	1
Event Input	2
Event Output	2

Environmental

Temperature

Operating	-40°C to +71°C
Storage	-40°C to +85°C

Humidity 95% non-condensing

Submersion 2 m for 12 hours (IEC 60529 IP68)

Water MIL-STD-810H, Method 512.6

Dust MIL-STD-810H, Method 510.7

Vibration (operating)
Random MIL-STD-810H, Method 514.8, Category 24, 7.7 g RMS

Sinusoidal IEC 60068-2-6

Acceleration (operating) MIL-STD-810H, Method 513.8, Procedure II (G Loading - 15 g)

Bump (operating) IEC 60068-2-27 Ea (25 g)

Shock (operating) MIL-STD-810H,Method 516.8, Procedure 1, 40 g, 11 ms terminal sawtooth

Compliance

FCC, ISED, CE[18]

Firmware Solutions

- Field upgradeable firmware and software models
- Configurable PPS output
- SPAN Enhanced Profiles
- ALIGN
- TerraStar PPP
- RTK
- RTK ASSIST
- API

Optional Accessories

- Power and I/O cable
- Mounting Plate
- VEXXIS series antennas
- Compact GNSS antennas
- NovAtel Application Suite
- GrafNav/GrafNet
- Inertial Explorer

Performance During GNSS Outages[20, 21]

Outage Duration	Positioning Mode	Position Accuracy (m) RMS		Velocity Accuracy (m/s) RMS		Attitude Accuracy (Degrees) RMS		
		Horizontal	Vertical	Horizontal	Vertical	Roll	Pitch	Heading
0 s	RTK[19]	0.02	0.03	0.015	0.010	0.010	0.010	0.030
	PPP	0.06	0.15					
	SP	1.00	0.60					
	Post-Processed[10]	0.01	0.02	0.015	0.010	0.003	0.003	0.010
10 s	RTK[19]	0.12	0.08	0.035	0.020	0.018	0.018	0.040
	PPP	0.16	0.20					
	SP	1.10	0.65					
	Post-Processed[10]	0.01	0.02	0.015	0.010	0.003	0.003	0.010
60 s	RTK[19]	3.82	0.73	0.165	0.030	0.030	0.030	0.055
	PPP	3.86	0.85					
	SP	4.80	1.30					
	Post-Processed[10]	0.11	0.05	0.017	0.010	0.004	0.004	0.014

1. Typical SPAN system performance values when using this IMU. Performance specifications subject to GNSS system characteristics, Signal-in-Space (SIS) operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multipath effects and the presence of intentional or unintentional interference. 2. Model-configurable to track L5/E5a (all / Galileo) through L2 (GPS) or L3/E5b/B2 (GLONASS / Galileo / BeiDou) through L2 (GLONASS). See manual for details. 3. The secondary antenna input does not support L-Band or SBAS signals. 4. Hardware ready for L3 and L5. 5. Requires an MFD model receiver. 6. E1bc support only. 7. GPS-only. 8. Requires subscription to TerraStar data service. Subscriptions available from NovAtel. 9. Requires SPAN Marine Profile. 10. Post-processing results using Waypoint Inertial Explorer. 11. Typical value. No almanac or ephemerides and no approximate position or time. 12. Typical value. Almanac and recent ephemerides saved and approximate position and time entered. 13. Time accuracy does not include biases due to RF or antenna delay. 14. Export licensing restricts operation to a maximum of 515 meters per second, message output impacted above 500 m/s. 15. Supplied by IMU manufacturer. 16. Dimensions do not include mounting feet. 17. Typical values using serial port communication without interference mitigation. Consult the OEM7 Installation & Operation User Manual for power supply considerations 18. Pending 19. 1 ppm should be added to all position values to account for additional error due to baseline length. 20. Outage statistics were calculated by taking the RMS of the maximum errors over a minimum of 30 complete GNSS outages. Each outage was followed by 120 seconds of full GNSS availability before the next outage was applied. High accuracy GPS updates (fixed ambiguities) were available immediately before and after each outage. The survey data used to generate these statistics had frequent changes in azimuth. 21. Outage performance achieved with one antenna.

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